

CONVOLUTION SPLINES BASE OF AN ARBITRARY CLASS OF DIFFERENTIABILITY

Praciano-Pereira, Tarcisio¹ and Neves, Antônio Jorge²

¹Univ. Est. Vale do Acaraú, Sobral, Brazil, tarcisio@member.ams.org

²U Aveiro, Aveiro, Portugal, jorgeneves@ua.pt

keywords: convolution splines base, convolution kernel, interpolation projector, Applications of Nonlinear Sciences.

Abstract

[]Praciano-Pereira, Tarcisio, Neves, Antônio Jorge
CONVOLUTION SPLINES BASE

1. INTRODUCTION

The basic tool is a partition of unity obtained through *regularization by convolution* of the characteristics of a partitioning of the interval $[A, B]$, using *kernel with compact support*. as has been done for example in [6].

1.1. Analysis of the computational algorithm

f is the n th power by convolution of $\chi_{[0,1]}$, here $n = 5$.

Here *kernel* as fixed element of a sequence that is an *approximate unit*, [9, ch 6, page 157] used as a convolution factor for regularization. Any convolution power of $\chi_{[0,1]}$, f is a kernel and in [5], we have established a algorithm to construct f for whatever n , a specific power will be pointed by the order foa differential operator under study. In this paper, $[0, m] = [A, B]$, where m is an integer representing the number of integer nodes of the partition. The transform equations of f for $[A, B]$ are

$$\eta(x) = nf(nx); \rho(x) = \eta(x + \frac{1}{2}); \rho_k = k\rho(kx); \quad (1)$$

$$R = B - A; w = \frac{m}{R}; \eta_w = w\eta(wx); \quad (2)$$

$$a(x) = \eta * \chi_{[0,1]}; a_w(x) = \eta_w * \chi_{[0, \frac{1}{w}]}; \quad (3)$$

$$\text{supp}(a_w) = [0, \frac{2}{w}]; \rho_{w,k} = k\rho_w(kx); \quad (4)$$

and $\rho_k = k\rho(kx)$ will be kernel we shall use.

A python class was built to represent the mathematical objects of this paper, to be soon published. We have used Riemann sums to have the integral of $h(x) = x^2$ on $[-1, 1]$ precise to 5th figure, integral of the kernel and its derivative precise up to 15th figure. Compared cosine and its convolution approximation at the $x = 3, 4, 7$ precise to 2nd figure. The Figure (1) at page 1, shows the graphics of $h(x) = \sin(3x + 7)(\frac{x}{2})^2$ and $h * \rho_{10}; \rho_{10} : x \mapsto 10\rho(10x)$; The graphics are overshadowing one another, $\|h(x) - (h * \rho_{10})(x)\| \leq 0.036; x \in [-10, 14]$ step $\text{delta} = 0.2$.

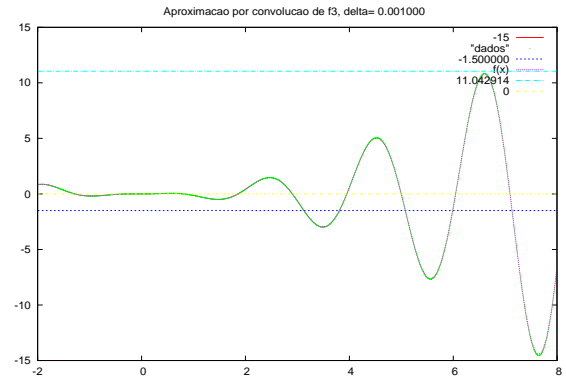


Figure 1 – convol. approx. of $h(x) = \sin(3x + 7)(\frac{x}{2})^2$

$\rho_{10})(x)\| \leq 0.036; x \in [-10, 14]$ step $\text{delta} = 0.2$.

2. CONSTRUCTION OF A PARTITION OF THE UNITY

The calculations sketch how to produce a splines partition of the unity:

$$f(x) = \chi_{[0,1]}^n; \eta(x) = nf(nx); m(\text{supp}(\eta)) = 1; \quad (5)$$

$$h_j(x) = h(x - j) = (h * \delta_j)(x); \quad (6)$$

$$\sum_{j=0}^m \chi_{[0,1]}(x - j) = 1 \text{ q.s.} \quad (7)$$

$$a = \eta * \chi_{[0,1]}; a_j(x) = a * \delta_j; \quad (8)$$

$$\eta * (\sum_{j=0}^m \chi_{[0,1]}(x - j)) = 1; x \in \mathcal{V}_{[1,m]} \quad (9)$$

$$(a_j)_{j \in \{0, \dots, m\}} = (a * \delta_i)_{i \in \{0, \dots, m\}}; \quad (10)$$

$\text{supp}(a)$ is an interval of measure 2, the successive j -translations coincides exactly over the half-interval, this makes the point for the optimization of the algorithm:

$$[0, m] \ni x \mapsto \sum_{j=0}^m a_j(x) = a_k(x) + a_{k+1}(x); k = [x] \quad (11)$$

Convolutions replaced by translations of the convolution already done, [5] the elements at Eq. (11), the partition relative to $[0, m]$; $m > 0; m \in \mathbf{N}$, but equations (4) - (7), will reset to the general case, power n , $[A, B]$, m nodes, a program to be published, shortly, under GPL does this.

3. INTERPOLATION PROJECTOR

To build the interpolation projector associated with a partition the interval $[0, m]$ we use the system of equations (5)-(10).

3.1. Projector $PU(g)$

Method: a trivial example generalized later. Graphic in Figure (2), page 2, is the linear interpolation of selected

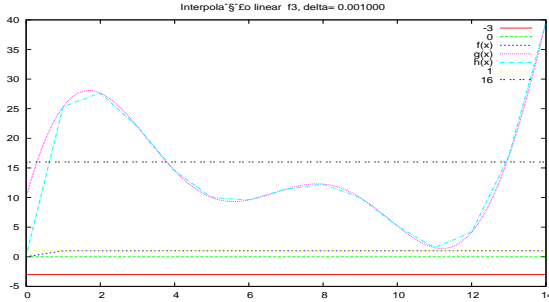


Figure 2 – Interpolation projector: linear interpolation of $g(x) = \sin(x/2)(x - 5)(x - 9) + 10$

points on the graph of g

The atom $a(x)$, Eq. (8) has support $[0, 2]$ at which translations have the peaking point of $a_j(x)$ to coincide with the minimum of $a_{j+1}(x)$, see Figure (3). The sum $\sum_{j=0}^m a_j(x)$ will

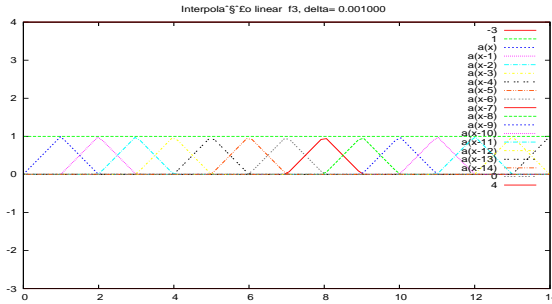


Figure 3 - integer translations of an atom of compact support

be a straight line at the Figure (3). Linear interpolation is the sum of the translations using coefficients $g(i)$ to $a(x - i)$, the integers nodes: the precision points. An other explanation,

$h(x) = \sum_{j=0}^m a_j(x)$ is the sum of the convolution products of

$\chi_{[j, j+1]; j=0 \dots m}$ with $\chi_{[0,1]}$. Put $\eta(x) = nf(nx)$ instead of $\eta = \chi_{[0,1]}$ to have a partition of unity of class C^{n-2} .

But the point here is the sum

$$\sum_{j=0}^m g(j)a_j \quad (12)$$

that leads to the expression of interpolation project we are searching for:

Definition 1 (Projector) interpolation projector

Consider the vector space $SP_m([0, m])$ generated by translations of atoms a defined in equation (8).

$$\sum_{j=0}^m g(j)a_j \quad (13)$$

defines an interpolation projector of the space of continuous functions $C([a, b], \mathbf{R})$ into the space $SP_m([A, B])$.

References

- [1] Latour V. Dahlke S., Dahmen W. Smooth refinable functions and wavelets obtained by convolution. *Applied and Computational Harmonic Analysis*, 2 (1):68–84, 1995.
- [2] Delvos F-J and Schempp Walter. *Boolean methods in interpolation a approximation*. Pitman research notes in Mathematics, 1989.
- [3] Awanou G., Lai Ming-Jun, and P. Wenston. The multivariate spline method for numerical solution of partial differential equations and scattered data interpolation. in *Wavelets and Splines: Athens 2005*, edited by G. Chen and M. J. Lai, Nashboro Press, in Wavelets and Splines: Athens 2005, edited by G. Chen and M. J. Lai, Nashboro Press, 2006:24–74, 2006.
- [4] J.M. Melenk and I. Babuska. The partition of unity finite element method: Basic theory and applications. *Seminar fur Angewandte Mathematik Eidgenossische Technische Hochschule CH-8092 Zurich Switzerland*, Research Report No. 96-01:23, 1996.
- [5] A.J. Neves and T. Praciano-Pereira. Convolutions power of a characteristic function. *arxiv.org*, 2012, April, 22:16, 2012.
- [6] T Praciano-Pereira. Splines por convolução. *Préprints da Sobral Matemática* <http://www.sobralmatematica.org/preprints>, 2007.09:10, 2007.
- [7] T. Praciano-Pereira. An interpolation projector associated to a non uniform partition. *Préprints da Sobral Matemática* <http://www.sobralmatematica.org/preprints>, 2008.08:10, 2008.
- [8] T. Praciano-Pereira. Convolução de funções características em r^2 . *Préprints da Sobral Matemática* <http://www.sobralmatematica.org/preprints>, 2011.05:10, 2011.
- [9] W. Rudin. *Functional Analysis*. McGraw-Hill Book Company, 1972.
- [10] et al. S. Pooseh. Approximation of fractional integrals by means of derivatives. *Computers and Mathematics with Applications*, 2012.